

Name: _____

Date: _____

RA1

R T B S R N N H R H X A S G E H Q
E Y R C O W O R K E N V E L O P E
S R M I T D S S P L I N E Q X L R
A R L T A M A E B H G U O R H T A
L H O A L F T P O S I T I O N R C
E A R M U Z O F Y G K P V A R K T
R R T E P R O S N E S H C U O T U
I M N N I T R A N S D U C E R M A
A O O I N T E R P O L A T I O N T
T N C K A R L N W R W I L L S G O
T I O X M T N A D N E P F G S W R
O C V A R T I C U L A T I O N M Y
L D R J A C O B I A N M A T R I X
M R E C C S I X A C A K X D W B M
P I S X R E V O L U T E J O I N T
U V O P T I C A L E N C O D E R C
T E W T N I O J Y R A T O R U Q T

Jacobian Matrix	Optical Encoder	Harmonic Drive	Revolute Joint
Interpolation	Servo Control	Work Envelope	Articulation
Rotary Joint	Through-Beam	Touch Sensor	Manipulator
Kinematics	Transducer	Actuator	Position
Pendant	Spline	Laser	Axis