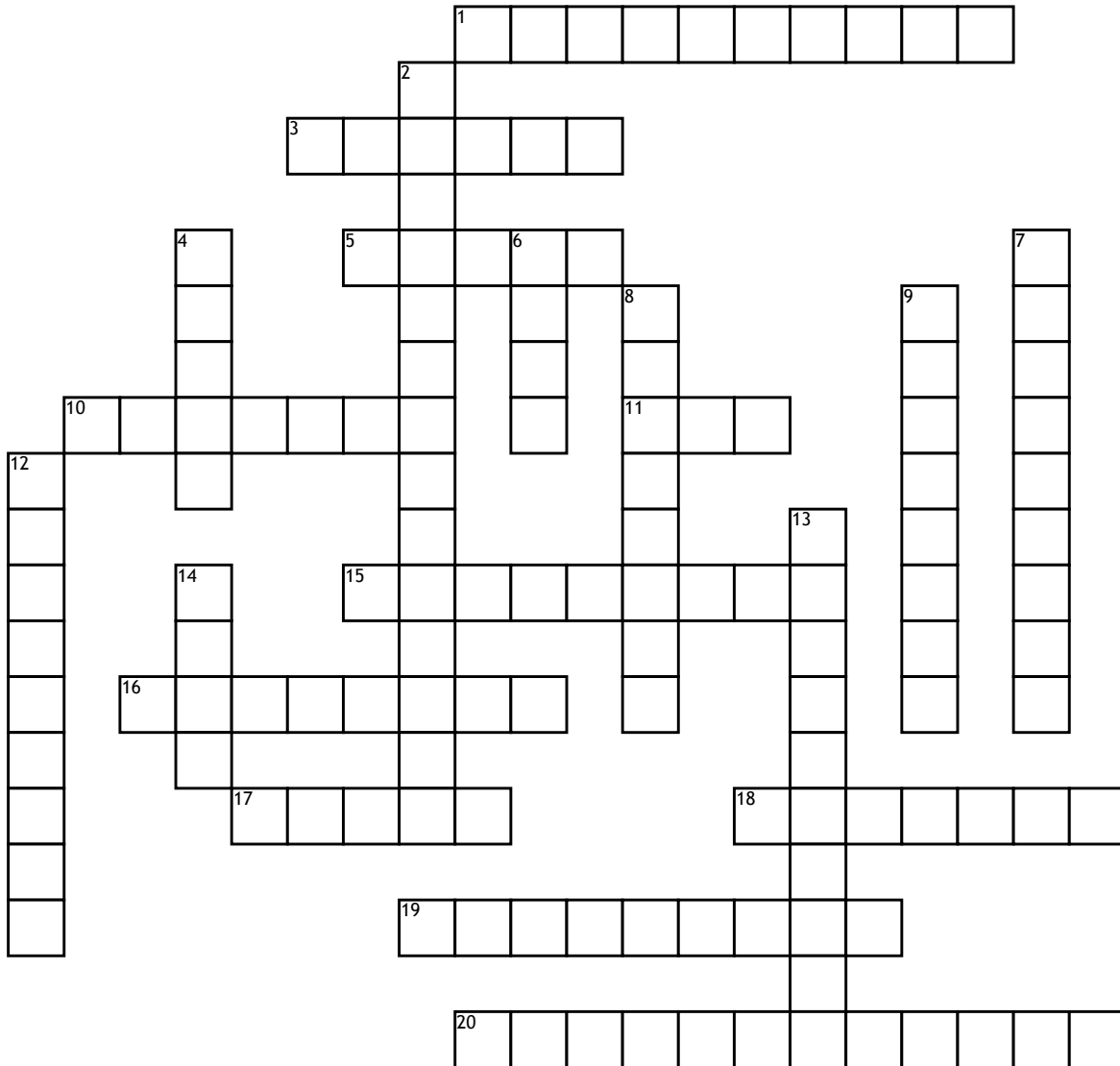


VEX EDR Sections 1-4 Crossword



Across

- 1. Spaces, tabs, and lines which make it easier for the programmer to write the code and others to read it; but is not read by the microcontroller.
- 3. What statement contains the configuration information for the motors and sensors?
- 5. If the left motor is moving forward and the right motor is stopped, the robot is turning in which direction?
- 10. Making the robot's movement slower makes the behaviors easier to.
- 11. The command line `wait1Msec(6000);` continues the previous code for ____ seconds
- 15. The command line `motor[rightMotor]=-63;` will make the right motor move _____.

- 16. Variances between motors, robot construction and _____ can cause motors to run at different speeds when the same power levels are applied.
- 17. Type of turn in which one motor is stopped and the other one is moving forward.
- 18. Type of behavior made up of two or more simple behaviors to tell the robot to accomplish a task or goal, like traveling through a maze.
- 19. Every command line must end with this character or punctuation symbol.
- 20. In the time control command line `wait1Msec();` the number in the parenthesis is time measured in _____.

Down

- 2. Punctuation and _____ are very important in coding.
- 4. Type of turn in which one motor is moving forward and the other motor is moving in reverse, at the same power level.

- 6. In VEX EDR, 63 represents what power level?
- 7. What does the positive/negative value in a motor's power level control?
- 8. Line of code that indicates that the program is about to start (AKA "Start Program" code)
- 9. Statements written after these symbols `//` or between these symbols `/**/`. They are not read as code by the robots.
- 12. When using wait time to control distance, if the power levels for the motors are decreased, the wait time must be _____ proportionally to reach the same distance.
- 13. Plan written in hybrid language halfway between English and programming language, which explains what the robot's performance.
- 14. Value applied to a motor that will cause it to stop.